

In the Claims:

1. (Previously Presented) A projectile retrieval system comprising:
a plurality of bullet stop and containment chambers;
a single transport mechanism disposed in communication with the plurality of bullet stop and containment chambers, the single transport mechanism having an elongate screw configured for carrying projectiles from the plurality of bullet stop and containment chambers to a remote location.
2. (Original) The projectile retrieval system of claim 1, further comprising a container disposed in communication with the transport mechanism for receiving projectiles from the transport mechanism.
3. (Original) The projectile retrieval system of claim 1, further comprising a motor for rotating the elongate screw.
4. (Withdrawn) The projectile retrieval system of claim 1, further comprising a manual crank for rotating the elongate screw.
5. (Original) The projectile retrieval system of claim 1, wherein the elongate screw has a central axis and at least one fin extending helically about the central axis in a first direction.
6. (Withdrawn) The projectile retrieval system of claim 5, further comprising at least one fin extending helically about the central axis in a second direction.

7. (Previously Presented) A projectile retrieval system comprising:

at least one bullet stop and containment chamber;

a transport mechanism disposed in communication with the at least one bullet stop and containment chamber, the transport mechanism having an elongate screw configured for carrying projectiles from the at least one bullet stop and containment chamber to a remote location; and

a control member between the at least one bullet stop and containment chamber and the transport mechanism to selectively prevent the passage of bullet fragments from the at least one bullet stop and containment chamber to the transport mechanism.

8. (Previously Presented) The projectile retrieval system of claim 7, wherein the control member has a first, closed position and a second, open position, and wherein the retrieval system further comprises a control member actuator for selectively moving the control member from the first, closed position to the second, open position.

9. (Previously Presented) The projectile retrieval system of claim 8, wherein the control member actuator is disposed in communication with a remote control input for selectively causing the control member actuator to move the control member between the first, closed position, and the second, open position.

10. (Previously Presented) The projectile retrieval system of claim 8, wherein the control member actuator is disposed in communication with an automatic detection sensor that senses the presence or absence of projectiles in the at least one bullet stop and containment

chamber and that causes the control member actuator to move the control member between the first, closed position, and the second, open position.

11. (Original) The projectile retrieval system of claim 1, further comprising a vacuum system for generating negative air pressure in the transport mechanism independent of the elongate screw.

12. (Previously Presented) The projectile retrieval system of claim 1, wherein the transport mechanism comprises a housing which is substantially airtight independent of connection to the at least one bullet stop and containment chamber.

13. (Previously Presented) A projectile retrieval system comprising:
a plurality of bullet stop and containment chambers disposed in a generally linear array;
a transport housing disposed in communication with the plurality of bullet stop and containment chambers for receiving bullets therefrom; and
a screw drive disposed in the transport housing for moving bullets through the transport housing.

14. (Previously Presented) The projectile retrieval system of claim 13, wherein the transport housing is substantially airtight other than its communication with the plurality of bullet stop and containment chambers.

15. (Previously Presented) The projectile retrieval system of claim 13, further comprising at least one control member disposed between one of the bullet stop and containment chambers

and the transport housing for selectively preventing bullets from entering the transport housing.

16. (Original) The projectile retrieval system of claim 15, further comprising a remote control for selectively opening the at least one control member.

17. (Original) The projectile retrieval system of claim 14, further comprising a vacuum system disposed in communication with the transport housing for selectively moving lead dust through the transport housing.

18.-21. (Cancelled)

22. (Previously Presented) The projectile retrieval system of claim 13, wherein a single screw drive is configured to move bullets from a plurality of bullet stop and containment chambers.

23. (Previously Presented) The projectile retrieval system of claim 13 further comprising a means for developing negative air pressure in the transport housing.

24. (Currently Amended) A projectile retrieval system comprising:
at least one bullet stop and containment chamber;
a transport mechanism comprising an elongate screw; and
~~a plurality of outlets~~ at least one outlet for releasing projectiles from the at least one bullet stop and containment chamber to the transport mechanism.

25. (Previously Presented) The projectile retrieval system of claim 24, wherein the transport mechanism comprises a housing disposed generally about the elongate screw.

26. (Currently Amended) The projectile retrieval system of claim 24, wherein the at least one outlet comprises a plurality of outlets ~~comprise~~ comprising a plurality of funnels.

27. (Currently Amended) The projectile retrieval system of claim 24, wherein the at least one outlet comprises a plurality of outlets and further comprising a plurality of control members disposed in communication with the plurality of outlets for regulating flow of projectiles into the transport mechanism.

28. (Previously Presented) The projectile retrieval system of claim 24, wherein the transport mechanism comprises a vacuum for creating negative air pressure in the transport mechanism.

29. (Previously Presented) The projectile retrieval system of claim 24, wherein the transport mechanism further comprises means for rotating the elongate screw.

30. (Previously Presented) The projectile retrieval system of claim 29, wherein the means for rotating the elongate screw comprises a motor.